

# Cut generation for facial disjunctive problems with two-term disjunctions

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# Outline of the talk

- ▶ Disjunctive programming with two-term disjunctions
- ▶ The cut generating linear program
- ▶ Special case: mixed 0-1 linear programming
- ▶ Generalisation to two term disjunctions
- ▶ Evaluation
- ▶ Final remarks

# Disjunctive programming with two-term disjunctions

- ▶ Disjunctive programs:

$$\begin{aligned} DP : \quad & \min_x c^T x \\ & \text{s.t. } Ax \geq b, \\ & x \geq 0, \\ & \bigvee_{i \in Q_k} d_i x \geq d_{i0}, \quad \forall k \in D \end{aligned}$$

- ▶ If  $|Q_k| = 2$ , then it is a *two-term disjunction*
- ▶ Let  $P := \{x \in \mathbb{R}^n \mid Ax \geq b, x \geq 0\}$
- ▶  $DP$  is *FACIAL* if every  $d_i x \geq d_{i0}$  represents a *face* of  $P$ :

$$F_i = \{x \in P \mid d_i x \geq d_{i0}\} \text{ is a face of } P$$

- ▶ In this talk only *FACIAL* disjunctive programs with two-term disjunctions occur

## Two-term disjunctions

- ▶ If  $DP$  is facial, w.l.o.g. every two-term disjunction

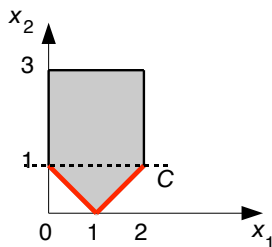
$$d_i x \geq d_{i0} \vee d_j x \geq d_{j0}$$

is equivalent to

$$-\tilde{A}_{k_1} x \geq -\tilde{b}_{k_1} \vee -\tilde{A}_{k_2} x \geq -\tilde{b}_{k_2}$$

for some  $(k_1, k_2) \in \{1 \dots, n+m\}^2$ , where  $(\tilde{A}, \tilde{b}) = \begin{pmatrix} A & b \\ I_n & 0 \end{pmatrix}$

## Two-term disjunctions (cont.)



► Example:

$$\min_{x_1, x_2} -x_2$$

$$\text{s.t. } x_1 + x_2 \geq 1$$

$$-x_1 + x_2 \geq -1$$

$$-x_2 \geq -3$$

$$-x_1 \geq -2$$

$$x_1, x_2 \geq 0$$

$$-x_1 - x_2 \geq -1 \vee x_1 - x_2 \geq 1.$$

## Disjunctive cuts

- ▶ To derive cuts, we add slack variables  $s = (s_1, \dots, s_m)$  to the linear program:

$$\begin{aligned}Ax - I_m s &= b \\ x &\geq 0\end{aligned}$$

- ▶ Let  $J$  index the non-basic variables in a basis of the linear program ( $J$  may index structural and slack variables as well, and we denote them together by  $s_J$ ). Suppose  $s_{k_1}$  and  $s_{k_2}$  are basic, i.e.,  $k_1, k_2 \notin J$ , and the simplex tableau has rows

$$s_{k_1} + \sum_{j \in J} \bar{a}_{k_1, j} s_j = \bar{a}_{k_1, 0} \quad \text{and} \quad s_{k_2} + \sum_{j \in J} \bar{a}_{k_2, j} s_j = \bar{a}_{k_2, 0}.$$

- ▶ The **disjunctive cut** with respect to  $J$  is

$$\sum_{j \in J} \pi_j s_j \geq \pi_0, \quad \text{where} \quad \begin{cases} \pi_j = \max\{\bar{a}_{k_1, j} \bar{a}_{k_2, 0}, \bar{a}_{k_2, j} \bar{a}_{k_1, 0}\}, & j \in J \\ \pi_0 = \bar{a}_{k_1, 0} \bar{a}_{k_2, 0} \end{cases}$$

## The cut generating linear program

- ▶ Given  $\hat{x} \in P$  such that  $\tilde{A}_{k_1}\hat{x} > \tilde{b}_{k_1}$  and  $\tilde{A}_{k_2}\hat{x} > \tilde{b}_{k_2}$ , find an inequality  $\alpha x \geq \beta$  which is valid for the convex hull of feasible solutions of  $DP$ , and cuts off  $\hat{x}$ .
- ▶ Applying Balas' results,  $\alpha, \beta$  can be found by solving the following LP:

$$\begin{aligned} (CGLP)_{k_1, k_2} \quad & \min_{(\alpha, \beta, u, v, u_0, v_0)} \alpha \hat{x} - \beta \\ \text{s.t.} \quad & \alpha - u\tilde{A} + u_0\tilde{A}_{k_1} = 0, \\ & \alpha - v\tilde{A} + v_0\tilde{A}_{k_2} = 0, \\ & \beta - u\tilde{b} + u_0\tilde{b}_{k_1} = 0, \\ & \beta - v\tilde{b} + v_0\tilde{b}_{k_2} = 0, \\ & u\mathbf{1} + v\mathbf{1} + u_0 + v_0 = 1, \\ & u, v, u_0, v_0 \geq 0. \end{aligned}$$

- ▶  $\alpha x \geq \beta$  is called **lift-and-project cut**.

## The mixed 0-1 programming special case

- ▶ The mixed integer program is

$$\begin{aligned} MIP \quad & \min_{x,s} c^T x \\ & Ax - I_m s = b \\ & x_i \in \{0, 1\}, \quad i = 1, \dots, p \\ & x, s \geq 0 \end{aligned}$$

- ▶ Disjunctions:  $x_i \leq 0 \vee x_i \geq 1$  for  $i = 1, \dots, p$  (binary variables)
- ▶ They correspond to the negation of constraints  $x_i \geq 0$  and  $x_i \leq 1$  of the LP relaxation of  $MIP$
- ▶ Let  $LP$  be the linear relaxation of  $MIP$

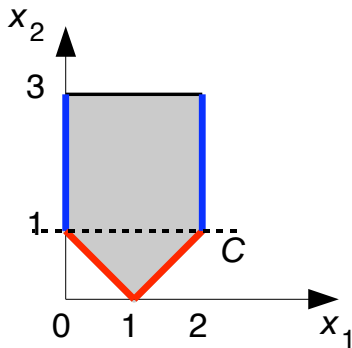
### Theorem (Balas & Perregaard)

Let  $\alpha, \beta, u_{M_1}, v_{M_2}, u_0, v_0$  constitute the basic variables in a feasible basis of  $(CGLP)_{k_1, k_2}$ . Then  $M_1 \cap M_2 = \emptyset$ ,  $|M_1 \cup M_2| = n$  and  $J = M_1 \cup M_2$  is the set of non-basic variables in a basis of  $LP$ .



## Counterexample for general two-term disjunctions

- ▶ In the general case, the previous **Theorem** does not hold:



- ▶ The **red** and the **blue** faces constitute a feasible basis of (CGLP), but it is impossible that the slack variables corresponding to the **blue** faces are simultaneously non-basic in the linear program.

# The converse Theorem in the general case

## Theorem

*Let  $J$  be the index-set of non-basic variables in a basis of the linear program. Then (CGLP) has a feasible basis with basic variables  $\alpha, \beta, u_{M_1}, v_{M_2}, u_0, v_0$  such that  $M_1 \cup M_2 = J$ . Moreover, the disjunctive cut  $\pi_{JSJ} \geq \pi_0$  and the lift-and-project cut  $\alpha x \geq \beta$  are equivalent.*

This result is more general than the following one:

## Theorem (Balas & Perregaard)

*In the mixed 0-1 programming case, let  $J$  be a set of  $n$  row indexes such that the square matrix  $\tilde{A}_J$  is non-singular. Then  $J$  corresponds to the  $n$  non-basic variables in some basis of the linear program. Moreover, (CGLP) admits a feasible basis with basic variables  $\alpha, \beta, u_{M_1}, v_{M_2}, u_0, v_0$  such that  $M_1 \cup M_2 = J$ . Moreover, the disjunctive cut  $\pi_{JSJ} \geq \pi_0$  and the lift-and-project cut  $\alpha x \geq \beta$  are equivalent.*

## Computations in the 0-1 case

- ▶ Main idea of Balas and Perregaard: mimic the steps of the simplex method for (CGLP) in the original tableau
- ▶ Observation: for  $i \notin J$  and  $j \in J$ ,

$$\begin{aligned}\bar{a}_{ij} &= -(\tilde{A}_i \tilde{A}_J^{-1}) \\ \bar{a}_{i0} &= \tilde{A}_i \tilde{A}_J^{-1} \tilde{b}_J - \tilde{b}_i\end{aligned}$$

- ▶ If  $0 < \hat{x}_k < 1$ , the corresponding row of the simplex tableau is

$$x_k + \sum_{j \in J} \bar{a}_{kj} = \bar{a}_{k0}.$$

- ▶ Balas and Perregaard have shown that the reduced costs  $r_{u_i}$  and  $r_{v_i}$  for  $i \notin J$  can be expressed with the  $\bar{a}_{ij}$ ,  $\bar{a}_{i0}$ ,  $\bar{a}_{kj}$  and the  $\hat{s}_j$ . If  $i \notin J$ , and  $j \in J$ , the value of the objective function in the basis  $(J \setminus \{j\}) \cup \{i\}$  can be expressed similarly.
- ▶ Using the above, (CGLP) can be "solved" in the original tableau with the revised simplex method.

## Computations in the general case

- ▶ We can generalise the formulae for  $r_{u_i}$  and  $r_{v_i}$  for general two-term disjunctions:

$$r_{u_i} = \sum_{j \in M_1} \bar{a}_{ij} \hat{s}_j - \sigma(1 + \xi_i) + \hat{s}_i - \frac{\bar{a}_{i0} \omega}{\theta}$$

$$r_{v_i} = \sum_{j \in M_1} -\bar{a}_{ij} \hat{s}_j - \sigma(1 - \xi_i) + \frac{\bar{a}_{i0} \omega}{\theta}$$

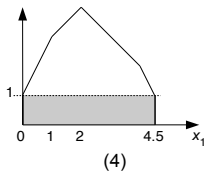
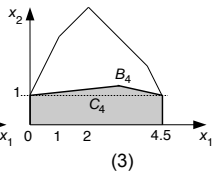
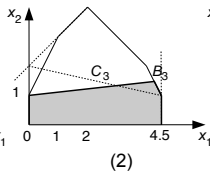
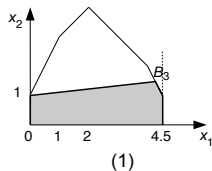
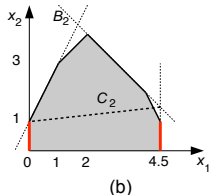
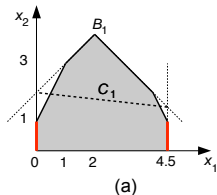
where  $\xi_i, \sigma, \theta$ , and  $\omega$  are expressions with the  $\bar{a}_{ij}, \bar{a}_{k_1,j}, \bar{a}_{k_2,j}$  and  $\hat{s}_j$ .

- ▶ We can also generalise the formula for computing the objective function after an exchange of variables in  $J$ .

# The limitations of the approach

- Consider the problem

$$\max x_2 \quad \text{s.t.} \quad (x_1, x_2) \in P, x_1 \leq 0 \vee x_1 \geq 4.5.$$



# Computational evaluation

- ▶ The LPEC instances

$$\begin{aligned} & \min_{(x,y)} c^T x + d^T y \\ \text{LPCC :} \quad & \text{s.t. } Ax + By \geq f, \\ & 0 \leq y \perp q + Nx + My \geq 0, \end{aligned}$$

where  $A \in \mathbb{R}^{k \times n}$ ,  $B \in \mathbb{R}^{k \times m}$ ,  $N \in \mathbb{R}^{m \times n}$ ,  $M \in \mathbb{R}^{m \times m}$ ,  
 $f \in \mathbb{R}^k$ ,  $c \in \mathbb{R}^n$ , and  $d \in \mathbb{R}^m$ .

- ▶ Problem data from  
Hu, J., Mitchell, J.E., Pang, J-S., Bennett, K.P., Kunapuli, G., On the Global Solution of Linear Programs with Linear Complementarity Constraints, SIAM J. Optimization, 19 (2008) 445-471.

# LPEC results

Table: General LPCCs with  $B \neq 0$ ,  $n = m = 50$ ,  $k = 55$ .

#	$lb$	$opt$	Hu et al.		L&P			
			LPs	IPs	nodes	cuts	rounds	time
1	28.7739	29.0501	21	2	8	29	7	0.43
2	36.1885	37.5509	229	9	14	51	8	0.83
3	33.8630	37.0022	4842	696	39	105	10	1.87
4	33.7618	34.2228	102	7	23	43	8	0.55
5	21.4187	22.2835	209	24	16	47	12	0.75
6	29.8919	30.0829	108	13	17	49	10	0.74
7	37.6712	38.0405	92	7	9	27	8	0.38
8	20.8210	22.3969	187	21	19	44	8	0.46
9	39.0227	40.3380	321	14	16	71	8	1.12
10	40.0135	41.3957	190	19	27	66	12	1.20

At most 50 pivots for generating a single cut.

## Comparison of cut generation methods

- ▶ On these instances, the best is not to generate any cuts: there are about 20% more nodes, but no time is spent on cut generation. Without cuts, the computation time is within 0.2 seconds on all instances.
- ▶ L&P cut generation is more than two times faster than CGLP cut generation.



## Final remarks

- ▶ Issues already solved: L&P cut generation, lifting of cuts (not included in this talk)
- ▶ Remaining open problems:
  - ▶ Strengthening of disjunctive cuts
  - ▶ **Remark:** In the mixed 0-1 programming case, integer modularisation gives cuts at least as strong as Gomory's mixed integer cuts, but without modularisation, the cuts are weak.
- ▶ Look at special cases with integer variables
  - ▶ The coefficients of the integer variables of a L&P cut  $\pi x \geq \pi_0$  can be strengthened by integer modularisation